

**AOT  
LAB**

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Computer Network

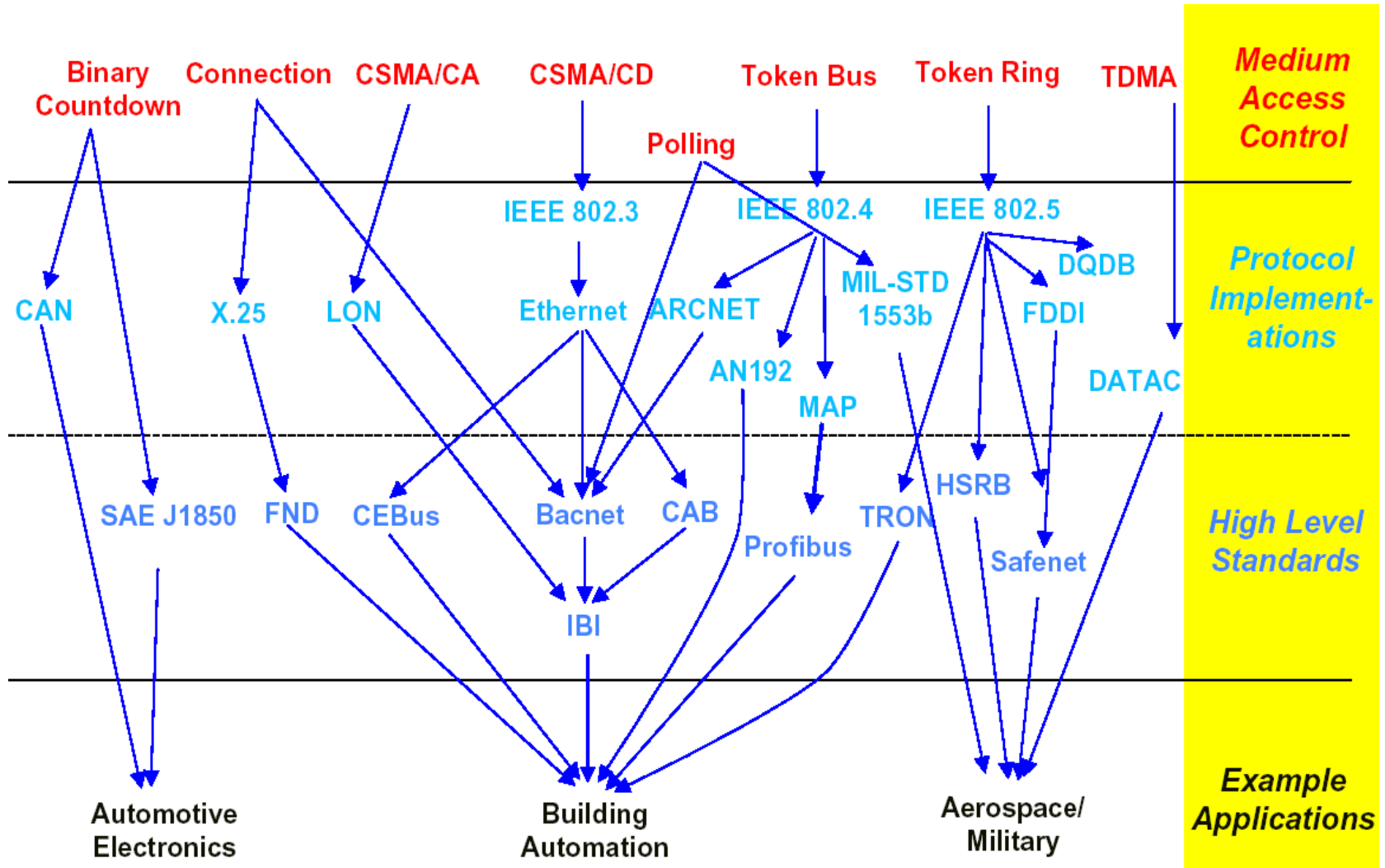
Embedded Network

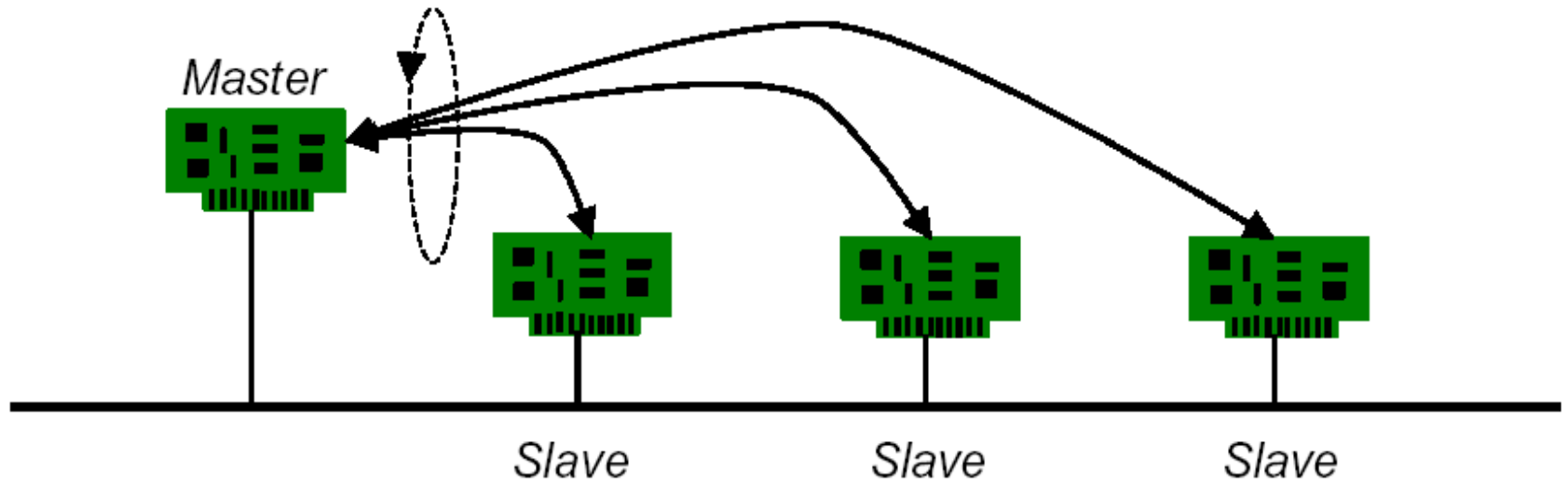
**Prof. Agostino Poggi**

- ◆ Heart of a each protocol stack is its MAC mechanism
  - Determinism
  - Efficiency
  - Priority
  - Optimization
  - Complexity
  - Cost
- ◆ Two directions
  - Adapt general protocols for embedded systems
  - Build specialized protocols

- ◆ Local priority
  - Each node can transmit its highest priority message when it gets a turn on the bus
  - Or, it can implement some form of round-robin message transmission, ...
- ◆ Global priority
  - Which node gets the next turn on the bus?
  - Could be a function of round-robin selection of nodes?
  - Could be a function of the node's inherent priority?
  - Could be a function of the priority of the highest message on the node – a “global message priority” scheme?
- ◆ Fundamental tension
  - Reducing latency for high-priority nodes/messages
  - Or, ensuring fairness/no starvation for low-priority nodes/messages

## Embedded Protocol Family Tree



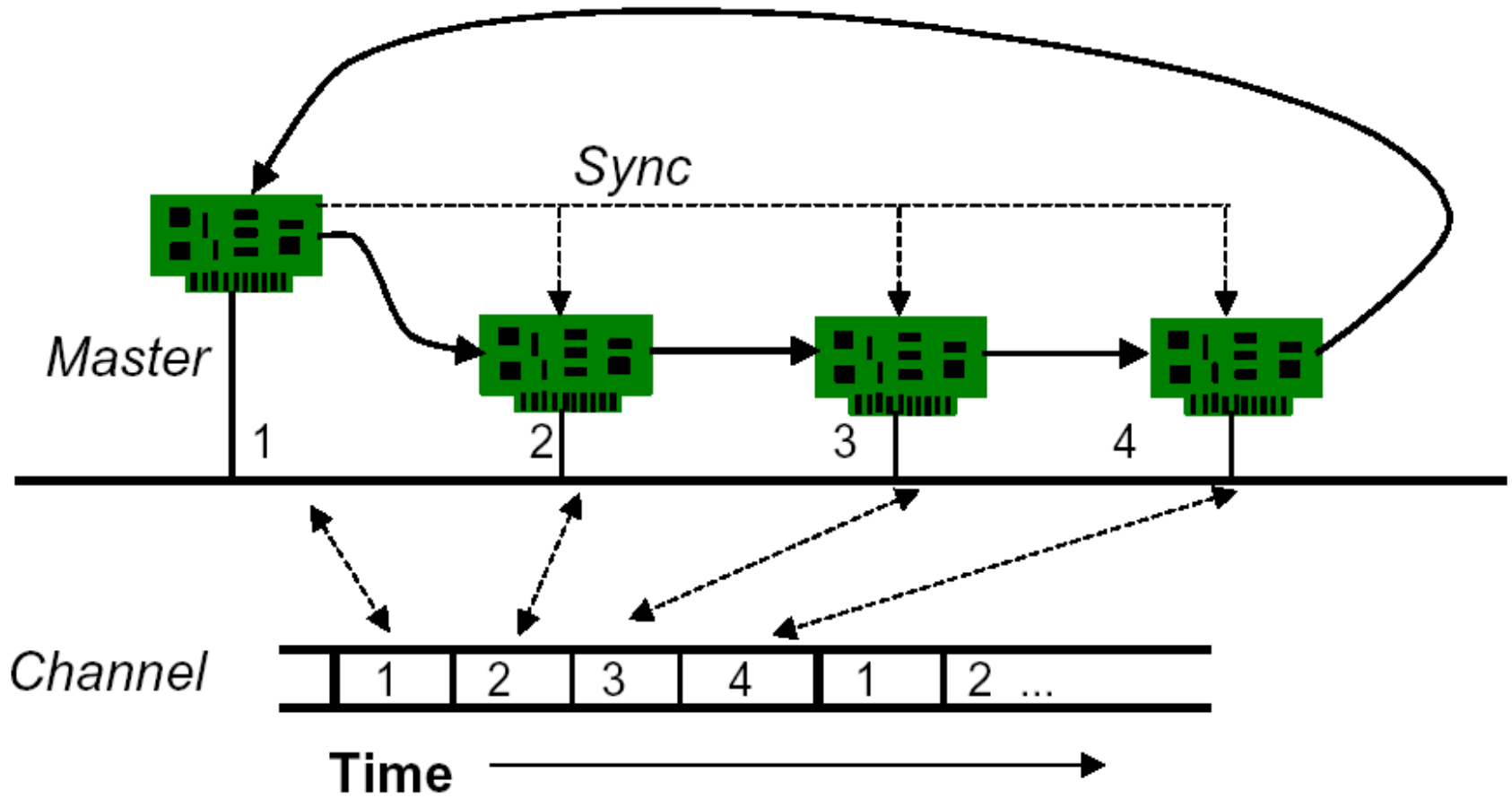


## ◆ Advantages

- Simple protocol to implement
- Historically very popular
- Bounded latency for real-time applications

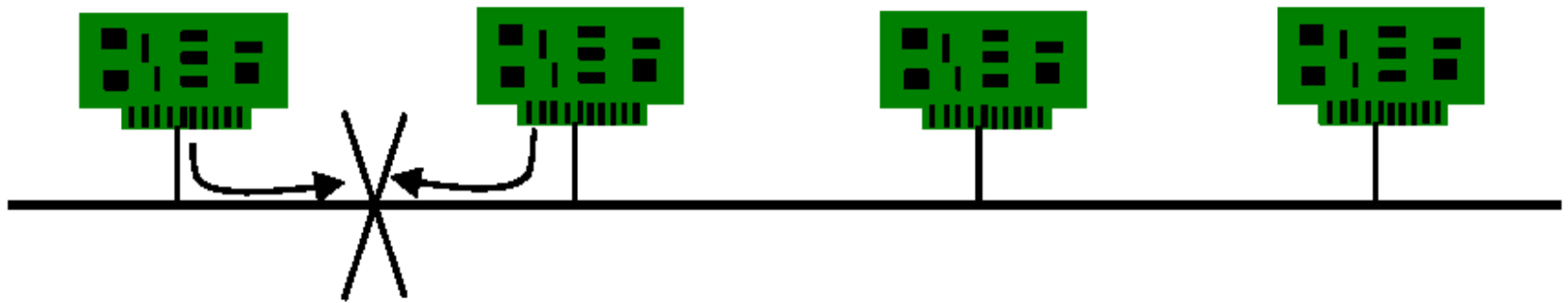
## ◆ Disadvantages

- Single point of failure from centralized master
- Polling consumes bandwidth
- Network size fixed during installation (not robust)
  - Or, master must discover nodes during reconfiguration
- Prioritization is local to each node
  - But can use centralized load balancing
  - Polling need not be in strict order; it could be, for example: 1, 2, 1, 3, 4, 1, 5, 1, 3, 1, 6, ... (repeats)



- ◆ Advantages
  - Simple protocol to implement
  - Deterministic response time
  - No wasted time for master polling messages
- ◆ Disadvantages
  - Single point of failure from the bus master
  - Wasted bandwidth when some nodes are idle
  - Requires stable clocks
  - Network size fixed during installation (not robust)
  - Prioritization is local to each node
    - Can use centralized load balancing
- ◆ Variation: Variable Length TDMA (~Implicit Token)
  - Unused time slices are truncated to save time
  - More efficient use of bandwidth



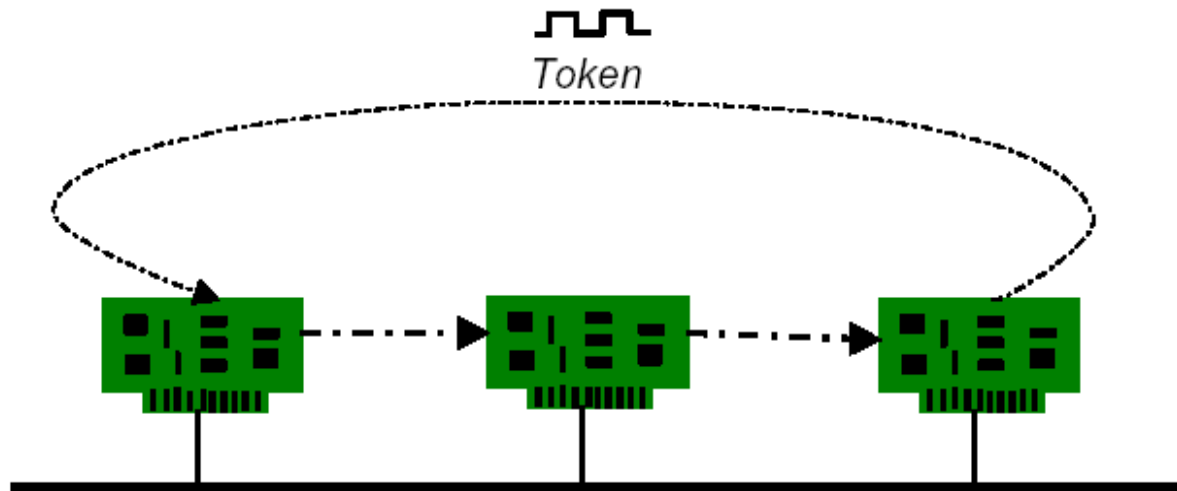


### ◆ Advantages

- Small latency for low traffic load
- Network initialization/configuration is not required
- Node can enter or leave the network without any interruption
- Supports many nodes
- Probabilistic global prioritization is possible
- Extensive installed base and support

### ◆ Disadvantages

- Designed for aperiodic traffic - not ideal for synchronized control loops
- Collision detection is an analog process which is not always practical
- Unbounded individual message latency
- Poor efficiency under heavy loads

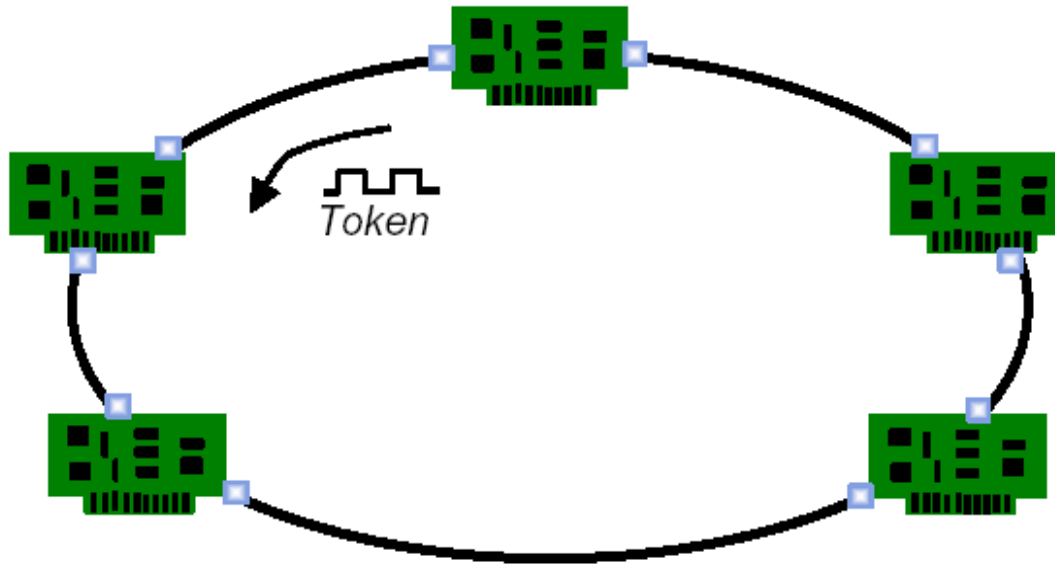


### ◆ Advantages

- Bounded latency for real-time control applications
- High throughput during heavy traffic
- On-the-fly reconfiguration

### ◆ Disadvantages

- Token passing latencies under light traffic conditions
- Prioritization local to each node
- Lengthy reconfiguration process
- Token initialization, loss, and duplication recovery overhead
- Collisions may occur during initialization and reconfiguration
- Complex protocol (especially at MAC sub-layer)

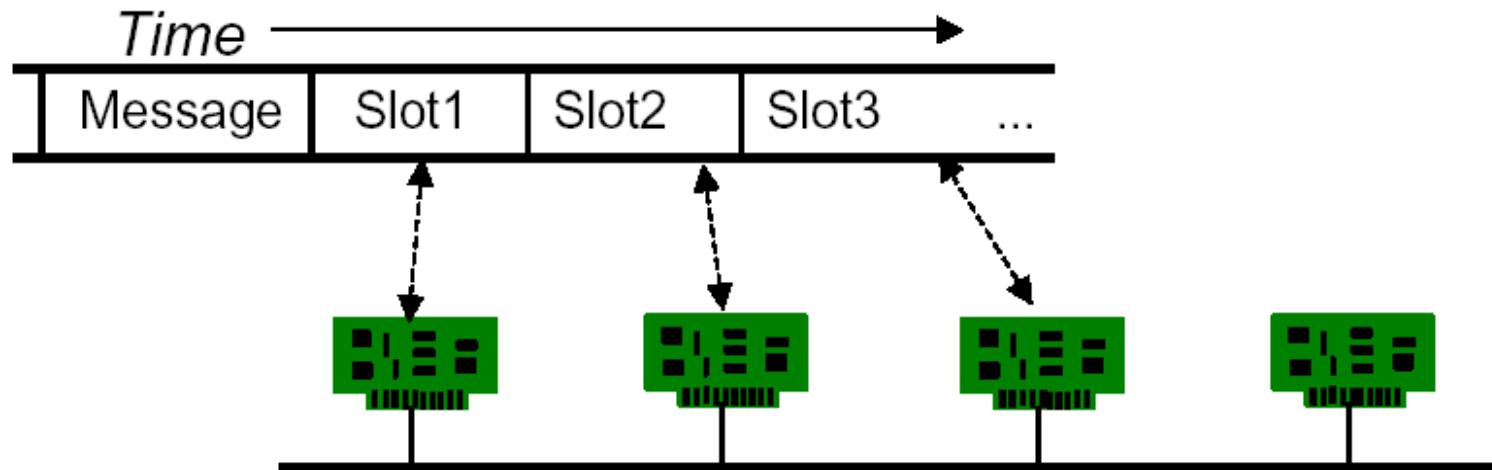


## ◆ Advantages

- Bounded latency for real-time control applications
- High throughput during heavy traffic
- Global and local priority mechanism available
- On-the-fly reconfiguration with node bypass hardware
- Well suited for fiber optic media
- Each station acts as a repeater - strengthens the signal

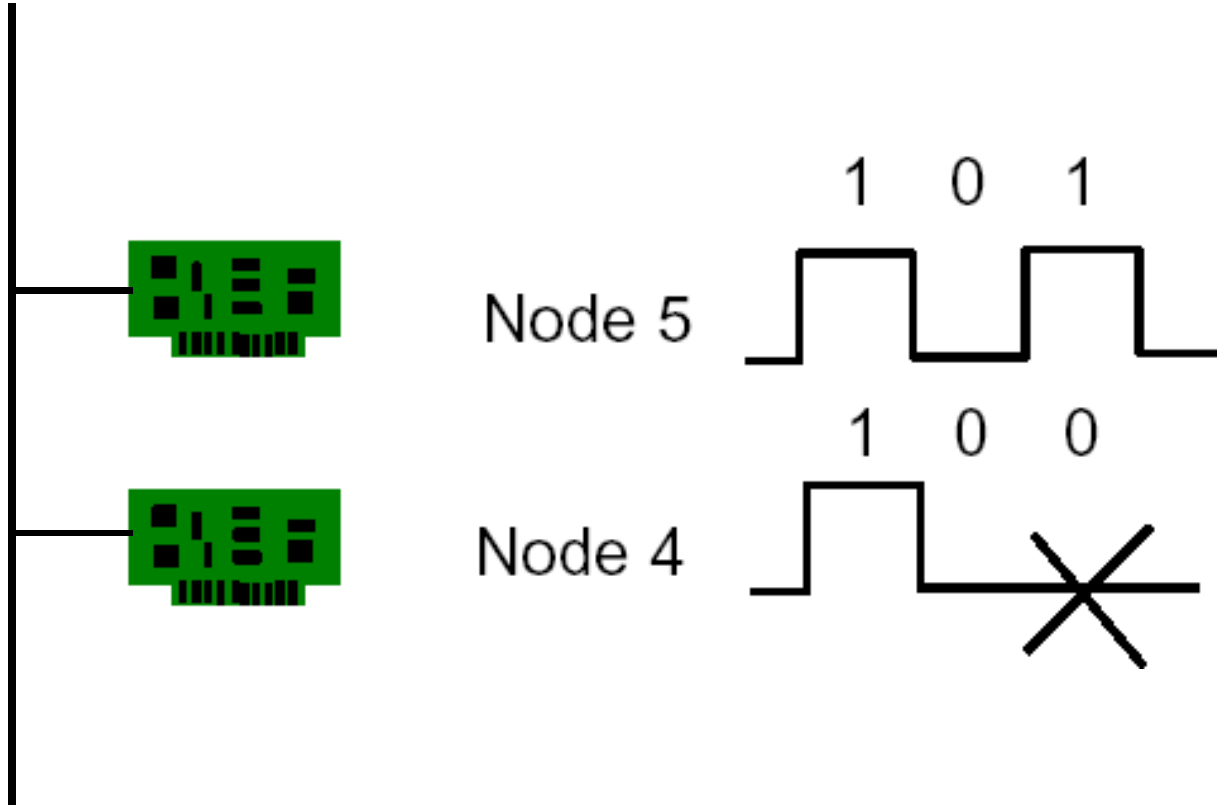
## ◆ Disadvantages

- Moderate latency for light traffic (token passing overhead)
  - Not as bad as token bus
- Centralized monitor (designated at initialization)
- Token initialization, loss, and duplication recovery overhead
- Propagation delay is based on the number of nodes
- Cut in the wire disables the entire network



- ◆ Advantages
  - Small latency for light traffic
  - Good throughput under heavy traffic
  - Global prioritization through fixed slots – prioritized implicit token passes
  - Bounded latency through rotating slots – non-prioritized implicit token passes
  
- ◆ Disadvantages
  - Restarting time slots from an idle bus can be difficult
    - Send dummy messages to avoid idle state
  - Collisions can occur





- ◆ Each node is assigned a unique identification number
- ◆ All nodes wishing to transmit compete for the channel by transmitting a binary signal based on their identification value
- ◆ A node drops out the competition if it detects a dominant state while transmitting a passive state
- ◆ Thus, the node with the highest identification value wins

## ◆ Advantages

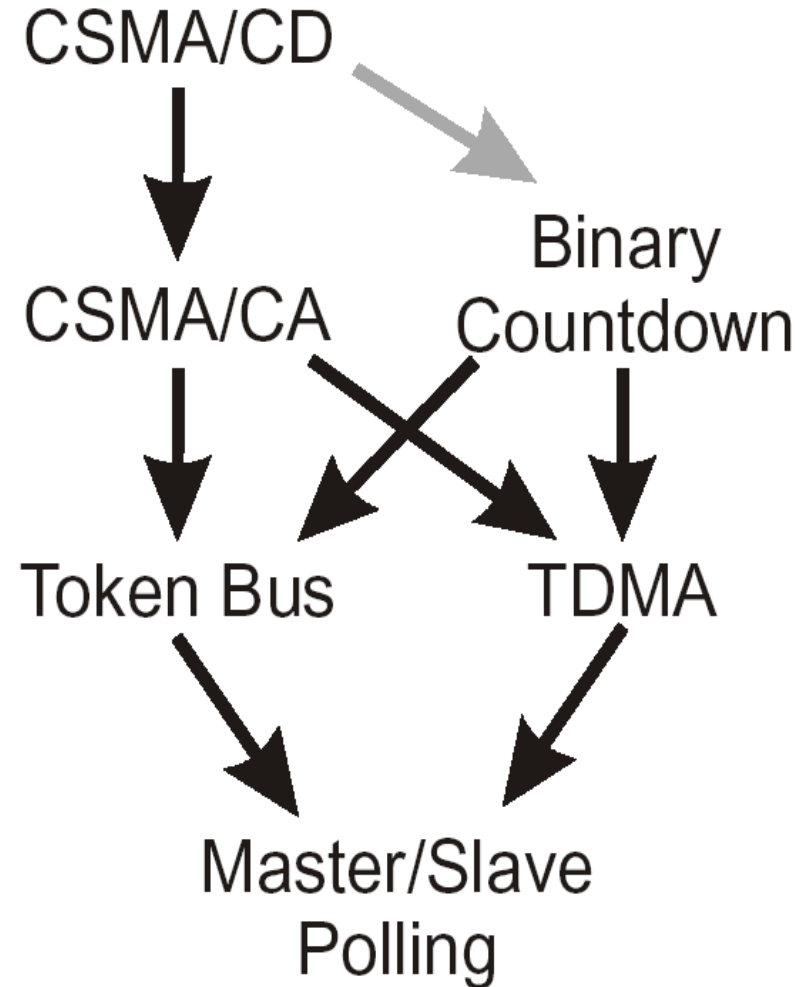
- High throughput under light loads
- Local and global prioritization possible
- Arbitration is part of the message - low overhead

## ◆ Disadvantages

- Propagation delay limits bus length (2 times the propagation delay of a bit)
- Unfair access - node with a high priority can "hog" the network
- Poor latency for low priority nodes

- ◆ Protocols are optimized for different operating scenarios
  - Collision-based
    - High number of possible transmitters
    - Low number of active transmitters
    - Arbitration overhead proportional to activity
  - Token-based, time-multiplexed & polled
    - Moderate number of total transmitters
    - Handles worst case activity without a problem
    - Arbitration overhead relatively constant
  - Binary countdown
    - Moderately large number of message types
    - Arbitration overhead constant
    - Global prioritization (but no mechanism for fairness)

- ◆ You can use one protocol to emulate another
- ◆ Use Ethernet (CSMA/CD) to emulate:
  - Master/slave polling – slaves only respond when polled
  - Token bus – use explicit token messages; application only transmits when it has the token
  - TDMA – slaves measure time from message from master and transmit appropriately
- ◆ But, there is no free lunch
  - “Slot” time involves round-trip through OS – longer than a couple bit times
- ◆ “Slice” time must account for CPU/OS jitter, not just HW oscillator drift



- ◆ Ethernet is becoming a low cost hardware
- ◆ A lot of embedded systems include
  - RTOS
  - Ethernet, TCP/IP and socket API
  - Data communication has not real-time constraints
    - Exchange of data is not critical
    - Exchange rate is low
- ◆ Some embedded systems need real-time communication
- ◆ Ethernet is not suitable for real-time performance
  - Ethernet MAC is CSMA/CD
  - CSMA/CD is not deterministic

- ◆ Real-Time Ethernet protocol does not inhibit CSMA/CD
- ◆ Real-Time Ethernet protocol places restrictions on the higher level software (application) which controls access to the medium
  - Only proprietary nodes on the net
  - Devices are divided into two sets
    - One device acts as controller node
    - All other devices act as remote nodes
  - Remote nodes may access the network bus until the controller sends a request to it
  - Remote nodes have a fixed amount of time to respond to a controller request

### ◆ Advantages

- Deterministic
- Easy to be implemented
- Support TCP/IP and socket API
- Low cost

### ◆ Pitfalls

- Centralized control
- Reduced performance



- ◆ Installation problems
  - Difficulties to add cables
  - Need of moving devices
  
- ◆ Solutions
  - Wireless network
  - Reuse pre-existing cables
    - Phone cables
    - Power cables

- ◆ Home Phoneline Network Alliance (HomePNA) uses phone lines as transport medium
- ◆ Frequency-division multiplexing (FDM) puts digital data on separate frequencies from the voice signals being carried by the phone line
- ◆ Operates at a constant rate even when the phone is in use

- ◆ HomePNA uses different technologies that support Ethernet protocol on phone lines
  - First standard
    - Tut Systems technology (1 Mbps)
  - Second standard
    - Epigram technology (10 Mbps)
  - Third standard
    - Planned (100 Mbps)
  
- ◆ Physical connection between computer and phone line network uses Universal Serial Bus (USB) adapter or HomePNA PCI card

### ◆ Advantages

- Cabling is not necessary
- Support TCP/IP and socket API
- Moderate cost

### ◆ Pitfalls

- CSMA/CD is not deterministic
  - Phoneline technologies are not appropriate for systems with tight timing deadlines

- ◆ Intellon's PowerPacket technology uses power line as transport medium
- ◆ Orthogonal Frequency-Division Multiplexing with forward error-correction puts digital data
  - Electrical subsystem frequencies (4.3 - 20.9 MHz) are split into 84 separate carriers
  - OFDM sends packets of data simultaneously along several of the carrier frequencies
    - Speed and reliability are increased
  - If noise or a surge in power usage disrupts one of the frequencies
    - PowerPacket chip will sense it and switch that data to another carrier

- ◆ Works independently from line voltage and frequency of power line used
- ◆ PowerPacket technology supports Ethernet protocol on power lines
  - First standard
    - Passport technology (350 Kbps)
  - Second standard
    - PowerPacket technology (14 Mbps)
  - Third standard
    - Planned (100 Mbps)
- ◆ Physical connection between computer and powerline network uses USB or Ethernet Interface

## ◆ Advantages

- Cabling is not necessary
- Support TCP/IP and socket API
- Moderate cost

## ◆ Pitfalls

- CSMA/CD is not deterministic
  - PowerPacket technologies are not appropriate for systems with tight timing deadlines

- ◆ Is the wireless version of Ethernet
  - Encrypts data to offer an equivalent level of privacy to insecure wired LAN
  
- ◆ Offers Wired Equivalent Privacy (WEP) security
  
- ◆ IEEE 802.11b supports
  - CSMA/CA
  - PCF



- ◆ Point Coordination Function (PCF) offers time critical services
  
- ◆ Point Coordination nodes manage traffic
  - CSMA/CA traffic is blocked
  - PC has a list of nodes requiring contention free services
  - PC coordinates nodes access via polling
  - After a certain interval without transmission nodes are removed from list

## ◆ Advantages

- Cabling is not necessary
- Support TCP/IP and socket API
- Equivalent level of privacy to insecure wired LAN
- Moderate cost

## ◆ Pitfalls

- CSMA/CA is not deterministic
- Deterministic traffic control is centralized

- ◆ Developed by Echelon
  - Used for a broad variety of applications
- ◆ Different types of transmission medium
  - Twisted pair, optical fiber, coaxial cable
  - Powerline
  - Radio
  - Infrared
- ◆ Operates up to 1.25 Mbps
- ◆ Uses small packets
  - Max payload is 229 bytes

- ◆ MAC is based on CSMA/CA
  - Collisions are possible
  - Collisions can be reduced by increasing the number of random slots
  
- ◆ LonTalk MAC predicts the bus traffic
  
- ◆ An optional collision detection circuit aborts communication early when collision is detected

## ◆ Advantages

- Different types of communication medium supported
- Complete set of communication services
- Low cost

## ◆ Pitfalls

- CSMA/CA is not deterministic
  - LonTalk is not appropriate for systems with tight timing deadlines

- ◆ Controller Area Network (CAN) has been developed by Bosch
  - Mainly used in industrial control device networks
- ◆ Transmission medium is twisted pair
- ◆ Operates up to 1 Mbps
- ◆ Uses very small packets
  - Max payload is 8 bytes
- ◆ Errors are automatically detected by CAN controller

- ◆ MAC is based on CSMA/CD+AMP (Arbitration on Message Priority)
  - Collisions are possible
  - Higher priority messages is guaranteed to gain bus access
  
- ◆ Each message is labeled by a 11 bits identifier
  - Unique through the network
  - Determines priority of message
    - Lower numerical value means higher priority
  
- ◆ Low bits are always dominant on the bus

- ◆ Two nodes send at the same time a message
  - Node 1 sends a higher numerical value identifier
    - Listens a low bit while sending a high bit
    - Stops transmission
  - Node 2 sends a low numerical value identifier
    - Listens its message identifier
    - Completes message transmission



## ◆ Advantages

- Fast, deterministic, prioritized performance with short messages
- Very reliable for error detection and fault confinement
- Low cost

## ◆ Pitfalls

- High speeds are only supported for short busses
  - 500m for 125 Kbps, 100m for 500 Kbps and 50m for 1 Mbps
- Limited set of network services
  - Additional services can be costly and tricky to implement
- Some applications require electrical isolation between bus and nodes
  - Hardware isolation makes the interface more expensive

- ◆ Developed by Apple Computer
- ◆ Mainly used for multimedia applications
- ◆ Standardized as IEEE-1394
- ◆ Transmission medium is a three-twisted pair shielded cable
  - Two for data, one for power
- ◆ Bus based on point-to-point links between devices
- ◆ Operates up to 400 Mbps
- ◆ Uses medium size packets
  - Typical payload is 2K bytes
- ◆ Synchronous and asynchronous data transfers

- ◆ Nodes are configured as logical tree
- ◆ Time is divided in cycles
- ◆ Each node can send a synchronous packet once a cycle
- ◆ Root node performs arbitration
  - Nodes send requests to their parent node
  - Node are enabled in an order depending on the distance from root node
- ◆ Remaining cycle time is dedicated to asynchronous traffic

- ◆ Root node performs the same kind of arbitration used for synchronous
- ◆ Nodes can send more than one packet
  - Nearest nodes might always win the arbitration
  - Nodes use fairness interval
- ◆ Nodes sending an asynchronous packet
  - Clear their arbitration enable bit
  - Wait for fairness interval deadline without traffic
  - Reset their arbitration enable bit
  - Try to get the bus

### ◆ Advantages

- Extremely fast, deterministic, performance
- Moderate cost

### ◆ Pitfalls

- Short distance between adjacent devices (~4,5 m)

- ◆ Infrared Direct Access (IrDA) is a standard for devices to communicate using infrared light pulses
- ◆ All remote controls use this standard
  - remote from one manufacturer can control a device from another manufacturer
- ◆ Infrared light use constraints devices to be in direct line of sight with each other
- ◆ All remote controls communicate with a master device
- ◆ Remote controls communicate on master request
- ◆ Operates up to 4 Mbps

## ◆ Advantages

- Cabling is not necessary
- Largely used
  - All remote control use this standard
- Low/moderate cost

## ◆ Pitfalls

- Short distance between adjacent devices
  - Few meters
- Devices must to be in direct line of sight with each other
  - At least an access point for room

- ◆ Bluetooth technology is a short range radio interface
  - Same purpose of infrared technology
  - Does not require line of sight
- ◆ Operates at 2.4 GHz up to 1 Mbps
- ◆ Bluetooth network is called piconet
- ◆ Two types of data transfer
  - Synchronous connection oriented (SCO) link
  - Asynchronous connection-less (ACL) link



- ◆ A piconet has a master and up to seven slaves
  - Master transmits in even time slots
  - Slaves in odd time slots
  
- ◆ Master reserves a set of slots for SCO links
  
- ◆ Slots not reserved for SCO links can be used for ACL links
  - One master and slave can have a single ACL link
    - point-to-point (master to one slave)
    - broadcast to all the slaves
  - ACL slaves can only transmit when requested by master

## ◆ Advantages

- Cabling is not necessary
- Does not require line of sight
- Privacy guaranteed by using unique public address, two secret keys and random number different for each transaction
- Moderate cost

## ◆ Pitfalls

- Short distance between adjacent devices (~10 m)
- Might interfere with other wireless communication